

# Simulation of Inextensible Hair and Fur

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seit 1558

- We focus on the fast simulation of hair and fur on animated characters.
- **Where is it used?** Films, computer games or related
- **Whats the difficulty?** The sheer number of hair strands and the fact that each hair is inextensible. Keeping thousands of deformable objects from being stretched is computationally expensive.
- To do this in **real time** and **naturally**.



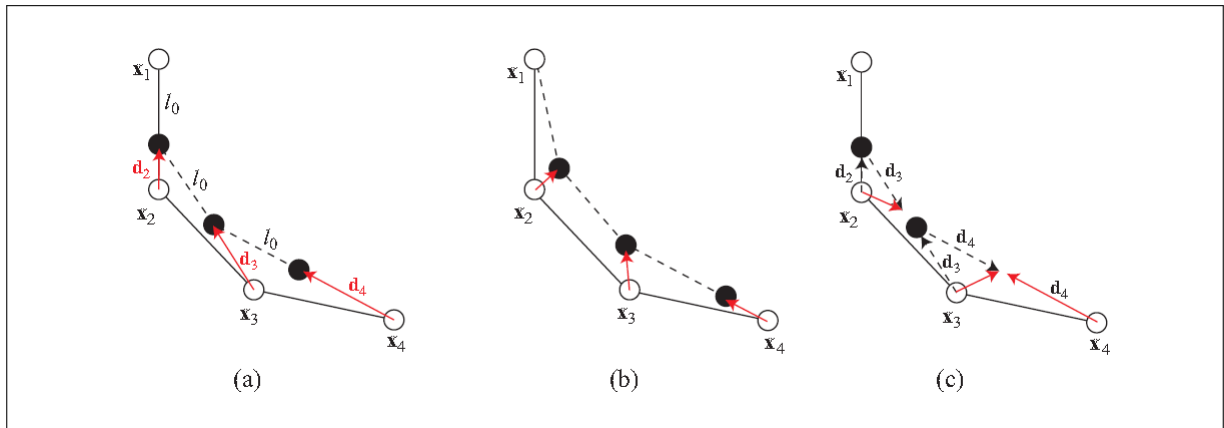
The following algorithm is described in:

M. Müller, T.Y. Kim, N. Chentanez, Fast Simulation of Inextensible Hair and Fur, Darmstadt, Germany, December 6-7 2012.

- We model a single hair by a chain of particles that is attached at one end  $(x_1, \dots, x_n)$ .
- All particles have the same distance  $l_0$  in between.
- We start at a particle that violate the distance constraints, commonly  $x_1$ .
- We iterate through all the particles once and move the particles such that all the constraints are satisfied.

Process called Follow-The-Leader (a).

- Process the particles in the order from 2 to  $n$ .
- Particle  $i$  has to be on a sphere with radius  $l_0$  around particle  $i - 1$ .
- Choose the point on the sphere that is closest to the original position  $x_i$ .



## To be dynamic

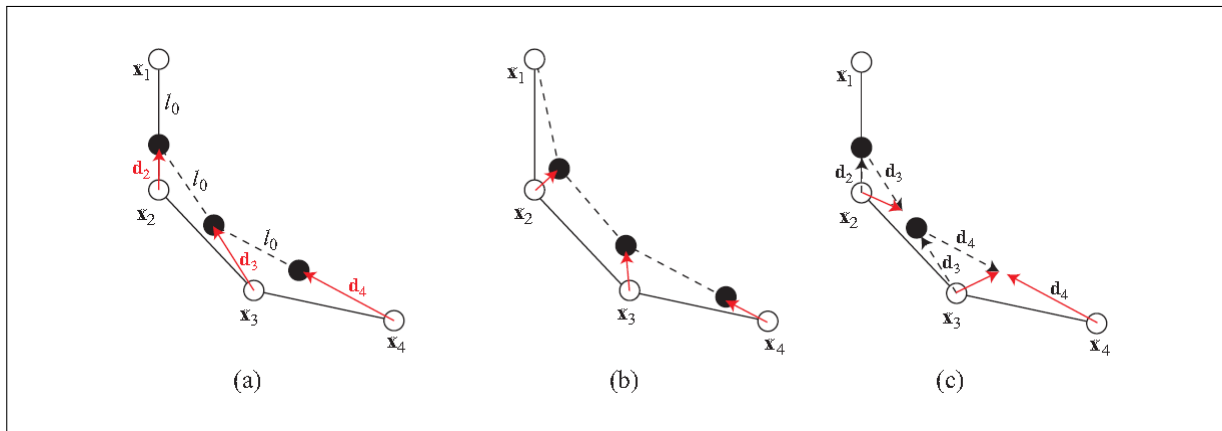
- Need to store and update velocities  $v_1, \dots, v_n$  along with the positions.
- A way to derive the velocity updates from the position updates is called **Position Based Dynamics (PBD)** (b).

$$x + \Delta t v + \Delta t^2 f \rightarrow p \quad (1)$$

$$\text{solve\_constraints}(p) \rightarrow p \quad (2)$$

$$\frac{x - p}{\Delta t} \rightarrow v \quad (3)$$

$$p \rightarrow x \quad (4)$$



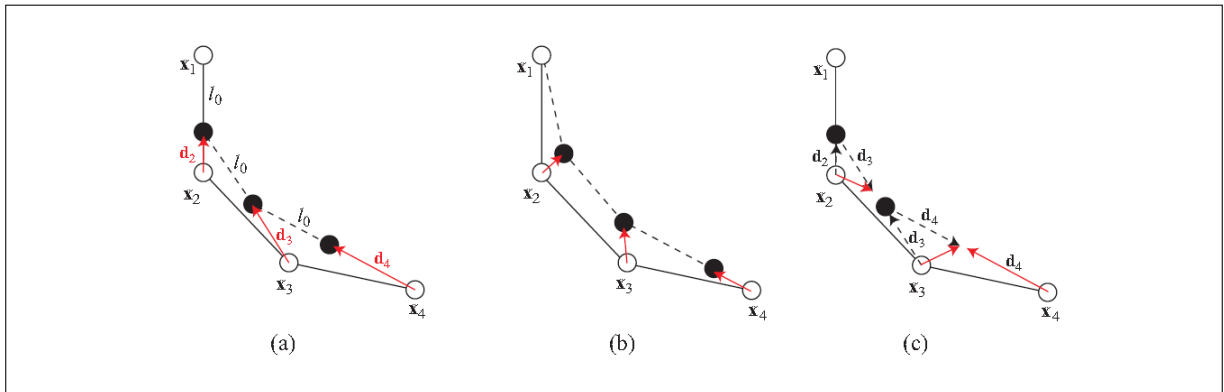
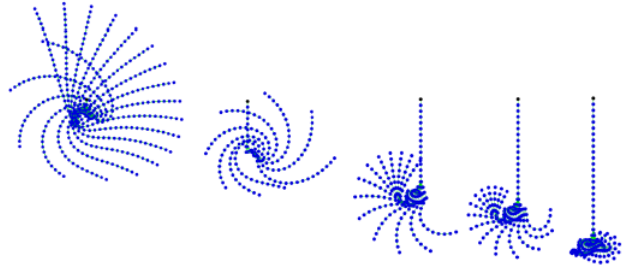
# What happened

Without respect to the mass of the particles, the method above ends up in a strange behavior.

To fix that bug we need a **velocity correction** by using damping (c).

$$\frac{x_i - p_i}{\Delta t} + s_{damping} \frac{-d_{i+1}}{\Delta t} \rightarrow v_i \quad (5)$$

With the correction vector  $d_i$  and  $s_{damping} \in [0, 1]$ .



## Our implementation

- OpenGL, openMP and SSE is used
- implementation of 2 different algorithms
- display and save simulation
- used aligned data-structure (64 byte without padding) for all vertexes
- potential of vectorization is high (speedup: 6 @ PBD, 16 @ FTL)
- measured average time of 10000 pictures with 1000 strands and 50 vertexes each
- speedup:

threads	2	4	8	12	16
FTL	1.4	2.6	5.1	7.6	9.7
PBD	1.4	2.6	5.2	7.6	10.0

